

IN THE TITLE

Please amend the title as follows:

SIGNAL PROCESSING DEVICE AND METHOD, SIGNAL
PROCESSING PROGRAM, AND RECORDING MEDIUM WHERE THE
PROGRAM IS RECORDED

IN THE SPECIFICATION

Please amend the specification as follows:

Please replace the paragraph beginning on page 8, line 26, with the following rewritten paragraph as follows:

-- The function for acquiring a discrete signal from a continuous waveform signal based on the fluency information theory is theoretically developed in detail and is defined as a sampling function in this description, as will be described later. The sampling function may be referred to as a fluency AD function. The function for acquiring a continuous waveform signal from a discrete signal is defined as an inverse sampling function in this description. The inverse sampling function may be referred to as a fluency DA function. The sampling function and the inverse sampling function defined as such maintain the orthogonal with each other and are expressed through the use of parameter m. --

Please replace the paragraph beginning on page 26, line 25, with the following rewritten paragraph:

-- Piecewise polynomials are defined by equation (3) and are continuously differentiable only (m-2) times. Equation (4) defines fluency signal space ${}^m S(\tau)$ as a signal space, using the function system (a set of functions)

$$\{ {}^m \phi(t - k \tau) \}_{k=-\infty}^{\infty}$$

composed of the piecewise polynomials of degree (m-1) as a base. As mentioned above, τ represents a sampling interval for acquiring a discrete

signal (sampling value) from continuous signals. Each sampling point along the time axis is represented as t_k ($= k\tau$).

$$\begin{aligned}
 & \left| \begin{aligned}
 & {}^m\phi(t) \underset{\substack{m \\ \text{def}}}{=} \int_{-\infty}^{\infty} \left(\frac{\sin \pi f \tau}{\pi f \tau} \right)^m e^{j2\pi f t} df \dots (3) \\
 & {}^mS(\tau) \underset{\substack{m \\ \text{def}}}{=} \left[{}^m\phi(t - k\tau) \right]_{k=-\infty}^{\infty} \dots (4)
 \end{aligned} \right. \\
 & \left. \begin{aligned}
 & {}^m\phi(t) \underset{\substack{m \\ \text{def}}}{=} \int_{-\infty}^{\infty} \left(\frac{\sin \pi f \tau}{\pi f \tau} \right)^m e^{j2\pi f t} df \dots (3) \\
 & {}^mS(\tau) \underset{\substack{m \\ \text{def}}}{=} \left[{}^m\phi(t - k\tau) \right]_{k=-\infty}^{\infty} \dots (4)
 \end{aligned} \right.
 \end{aligned}$$